This report demonstrates that the design safety margin employed when designing the reinforced concrete structure of an in-ground LNG tank can be reduced through the use of a more sophisticated analytical methodology, thus streamlining construction. In conventional design, a method of equivalent linear analysis is applied to determine the amount of reinforcement required to achieve a particular ultimate sectional strength, even for Level 2 earthquake motion. The more sophisticated approach is to apply dynamic nonlinear analysis, after determining the amount of reinforcement required to withstand Level 1 motion, and then ensuring that ductility adequate to withstand Level 2 motion. The application of this more sophisticated analytical method makes it possible to more accurately analyze the behavior of members, thus not only reducing the amount of reinforcement needed but also improving safety.

Key Words: In-ground LNG tank, dynamic nonlinear analysis, streamlining reinforced concrete structure

Mr. Nobuhiro KAIZU is a Senior Researcher at the Power Engineering R&D Center of TEPCO, Japan. He received his Master of Engineering Degree from Nagaoka University of Technology in 1982. His research interest is the seismic design of in-ground Reinforced Concrete structures. He is a member of the JSCE.

Mr. Mitsuo HARADA is a Manager of the Thermal & Nuclear Power Facilities Group at TEPCO Construction Engineering Center. He received his Master of Engineering Degree from Tohoku University in 1981. His research interest is the seismic design of Reinforced Concrete structures. He is a member of the JSCE and JCI.

Mr. Nobuharu KOYAMA is a Manager of the LNG Facilities Design Group, in the Thermal & Nuclear Power Civil Engineering Department of Tokyo Electric Power Services Co., Ltd., Japan. He graduated from Hosei University in 1980. His research interest is the design of LNG facilities including in-ground LNG tanks. He is a member of the JSCE and JCI.
Mr. Tsutomu KANAZU is a Director of the Materials Science and Structural Engineering Department at the Abiko Research Laboratory of the Central Research Institute of the Electric Power Industry, Japan. He received his Master of Engineering Degree from Tokyo Institute of Technology in 1978. His research interests are the performance-based design of underground reinforced concrete structures and the mechanical behavior of RC structures under high and low temperatures. He is a member of the JSCE, JCI and ACI.

Dr. Koji MIYAMOTO is the General Manager of TEPCO’s Civil and Building Engineering Center, Japan. He received his Doctor of Engineering Degree from Tokyo University in 1995. His research interest is the application of performance-based design. He is a fellow of the JSCE and a director of JCI.
1. INTRODUCTION

This report describes a method that can be used to verify the seismic performance of a three-dimensional
in-ground concrete structure during an earthquake based on "Guidelines for Verification of Structural
Performance of In-ground LNG (Liquefied Natural Gas) Tank Structures" (JSCE Committee of Civil
Engineering for Energy Equipment, 1999) [1]. The wall of an in-ground LNG tank is adopted as the
model.

In-ground LNG tanks are used to store LNG. They are designed such that the LNG is always at or below
the level of the surrounding ground. The JSCE guidelines relate to in-ground LNG tanks that have a
reinforced concrete in-ground structure consisting of the main structure, walls and a bottom slab. A
membrane (consisting of a thin metal film designed for low-temperature) fitted within the reinforced
concrete structure retains the LNG.

The guidelines describe the basic concepts and methods to be used for determining and verifying
structural performance during the performance-based design of such reinforced concrete structures. In
setting a framework for performance-based design, the guidelines have two principle aims:

(1) To ensure that suitable levels of safety and serviceability are achieved in the design of the main
structure of an in-ground LNG tank, thus ensuring that it can withstand external forces such as
strong earthquake motion.
(2) To achieve more streamlined and efficient design for a tank structure specific to a particular
location on the basis of the latest technologies and knowledge, and at the same time to promote
technological development toward more streamlined design.

In accordance with the intent of the newly introduced performance-based design approach, the
guidelines give basic concepts and methods for determining and verifying the structural performance of
main structure. At the same time, they offer more than one option as regards the verification method.

Four I analytical methods are given in the guidelines for obtaining the response of a structure to
earthquake motion, depending on the level of the earthquake motion and seismic performance to be
checked (Table 1.1). The methods range from traditional approaches to futuristic and ideal techniques.
A designer can select whichever is suitable. In this case study, a method of verification for Seismic
Performance 3 in the case of Level 2 earthquake motion is described for use when Method 2 or 3 is
adopted.

The results of verification for Methods 2 and 3 are compared, and the influences of different analysis
methods and seismic performance levels on the results (specifically the reinforcement arranged) are
evaluated. Finally, it is suggested that the use of a more sophisticated method can lead to better
streamlining (Figure 1.1).

Analysis methods given in the guideline

Method 1: Quasi-dynamic linear analysis method
   (response displacement method) [2]
Method 2: Quasi-dynamic equivalent linear analysis method
   (response displacement method) [3]
Method 3: Dynamic nonlinear analysis method
(structure: member nonlinearity, soil: total stress) [4]
Method 4: Dynamic nonlinear analysis method
(structure: material nonlinearity, soil: effective stress) [5] [6]

Table 1.1 Dynamic analysis methods for LNG tanks

<table>
<thead>
<tr>
<th>Method</th>
<th>Method 1</th>
<th>Method 2</th>
<th>Method 3</th>
<th>Method 4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Quasi-dynamic linear analysis method</td>
<td>Quasi-dynamic equivalent linear analysis method</td>
<td>Dynamic nonlinear analysis method (structural characteristics: nonlinearity of members, ground characteristics: total stress)</td>
<td>Dynamic nonlinear analysis method (structural characteristics: nonlinearity of materials, ground characteristics: effective stress)</td>
</tr>
</tbody>
</table>

Determined input ground motion
- Single level
- Multiple levels

Input value for analysis
- Response displacement of ground (simultaneous distribution calculated from ground response analysis)
- Time history of acceleration waves (input to design ground)

Static or dynamic analysis
- Response displacement method (static analysis)
- Time history response analysis (dynamic analysis)

Analysis model
- Separate or coupled analysis
- Ground property: Ground spring: Elasto-plastic model
- Structural characteristics:
  - Linear Initial stiffness (Thermal stress: 1/2 $E_0I_0$)*
  - Linear Equivalent stiffness (stiffness decrease)
  - Nonlinear Member-level 1, history-dependent macro model
  - Nonlinear Constitutive rule that materials Cracking and yielding of reinforcement are considered directly.

Major response values to be analyzed
- Sectional force
- Curvature and strain of element, and sectional force
- Indicator that directly represents the deformation (residual displacement) or damage for entire structure

Check items for the main structure
- Sectional force (checking of allowable stress)
- Sectional force (checking of limit state)
- Strain of element, and sectional force (transverse shear)
- Overall stability of the entire structure

* Initial stiffness ($E_0I_0$) is reduced by half when thermal stress is taken into consideration.
** In this case study, linear model with final stiffness calculated by one dimensional equivalent linear analysis

Design conditions
- Dimensions, geological condition and materials used

Determine the structural performance of in-ground tank

Determine normal and earthquake loading

Select analysis method, and earthquake loading

Determine seismic performance check indexes, and limit values

Determine safety factors

Verification of Seismic Performance 1 for Level 1 earthquake motion in the elastic zone
(this step is common to Methods 2 and 3, Method 2 is selected as representative

Verification of Seismic Performance 3 under the influence of Level 2 ground motion

Method 2
- Check for cross-sectional failure

Method 3
- Check deformation capacity

Figure 1.1 Review procedure in the case study
2. DESIGN CONDITIONS

2.1 Dimensions

The major dimensions and structure of the in-ground LNG tank to be designed in the case study are shown in Table 2.1 and Figure 2.1, respectively. The main structure of the tank has an inner diameter of 69.9 m and a cylindrical shape. It is embedded in the ground. The tank consists of walls, a bottom slab and roof. Diaphragm walls are constructed outside the tank walls to allow for excavation work.

<table>
<thead>
<tr>
<th>Item</th>
<th>Dimension</th>
</tr>
</thead>
<tbody>
<tr>
<td>Internal diameter of main structure</td>
<td>69.9 m</td>
</tr>
<tr>
<td>Height of wall</td>
<td>37.8 m</td>
</tr>
<tr>
<td>Thickness of component</td>
<td></td>
</tr>
<tr>
<td>Wall</td>
<td>1.8 m</td>
</tr>
<tr>
<td>Bottom slab</td>
<td>6.0 m</td>
</tr>
<tr>
<td>Diaphragm wall</td>
<td>1.1 m</td>
</tr>
<tr>
<td>LNG level</td>
<td>33.5 m</td>
</tr>
<tr>
<td>Height of the fill</td>
<td>AP+14.0 m</td>
</tr>
<tr>
<td>Embedded depth of diaphragm wall</td>
<td>AP-55.0 m</td>
</tr>
</tbody>
</table>

Figure 2.1 Structure of in-ground LNG tank

2.2 Geological conditions

The soil at the model point consists of fill at depths AP+14.0 m to AP+4.7 m, landf111 at AP+4.7 m to AP-6.1 m and diluvium at AP-6.1 and below. The fill around the tank has been consolidated enough to have an N-value of about 15. At the point, there exists a highly dense diluvial sandy layer uniformly, so the seismic design basement is set at AP-59.8 m.

2.3 Materials used
(1) Concrete
- Specifications: Ready mixed concrete satisfying JIS A 5308 with a nominal strength of 24 N/mm$^2$
- Characteristic compressive strength: $f_{ck}$-24 N/mm$^2$
- Young’s modulus: $E_c$=25 kN/mm$^2$
(2) Reinforcement
- Specifications: SD345, steel bar satisfying JIS G 3112
- Characteristic yield strength under tension: $f_{yk}$=350 N/mm$^2$
($370 \text{ N/mm}^2$: used for verification of seismic performance under the influence of Level 2H earthquake motion)
- Young's modulus: $E_s$=210 kN/mm$^2$

3. STRUCTURAL PERFORMANCE OF IN-GROUND LNG TANKS

In-ground LNG tanks are required to meet certain safety and serviceability requirements. These performance requirements are expressed in non-technical terms. However, the structural performance of an in-ground tank must be expressed in terms of engineering quantities as targets for design. Thus, normal and seismic performance levels are determined in terms of load-carrying capacity and watertightness. The service life an in-ground tank is set at 50 years.

3.1 Normal performance

The normal in-operation structural performance of the main structure of an in-ground tank must be defined such that load-carrying capacity and watertightness are adequate to meet normal safety and serviceability requirements. It must also be adequate to ensure that the tank remains usable for its service life without the need for major repairs.

3.2 Seismic performance

A major characteristic of earthquake activity is that strong earthquakes likely to have an effect on a tank are less likely to occur during its service life than less influential, weaker earthquakes. The rational approach, therefore, is to set seismic performance levels according to the probability of occurrence of different levels of earthquake motion such that the required level of safety attained. One aim of the guidelines is to clarify the required anti-seismic performance, including performance during the probable maximum earthquake, taking into account the importance of the tank, while at the same time streamlining the design process. The guidelines, therefore, set three different levels of earthquake motion and seismic performance. The required and target performance levels for the three levels of seismic performance are listed in Tables 3.1, 3.2, and 3.3.

3.2.1 Earthquake motion for verification

Three levels of earthquake motion are defined for verification purposes: levels 1, 2L, and 2H. Level 2 earthquake motion is divided into two sub-levels, 2L and 2H, according to probability of occurrence. This division into multiple levels is thought to offer a better guarantee of performance for important structures while leaving room for design streamlining.

- Level 1 earthquake motion: earthquake motion of intensity likely to be encountered once or twice during the service life of the in-ground tank
- Level 2L earthquake motion: strong earthquake motion with a relatively low probability of
occurrence at the tank location during the service life of the tank
Level 2H earthquake motion: very strong earthquake motion with an extremely low probability occurrence at the tank location during the service life of the tank

3.2.2 Combination of earthquake motion and seismic performance
The performance required of an in-ground tank is divided into the three levels outlined below.

Seismic performance level 1: structural performance during and immediately after an earthquake is such that the tank remains safe, loss in serviceability is not substantial, and the tank remains usable without major repair.

Seismic performance level 2: earthquake-induced loss in structural performance is not so great as to jeopardize tank safety. The tank remains usable without major repairs.

Seismic performance level 3: the main structure remains intact, and LNG storage is protected. With repairs, the tank can continue in use.

Seismic performance levels 1, 2, and 3 are combined with earthquake motion levels 1, 2L, and 2H, respectively (see Table 3.4).

<table>
<thead>
<tr>
<th>Table 3.1 Performance of in-ground level tank during an earthquake</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Variation of performance</strong></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Safety</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Required performance</td>
</tr>
<tr>
<td>Focus of owners or managers</td>
</tr>
<tr>
<td>Serviceability (effect on the function of LNG base)</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>

- 7 -
Table 3.2 Load-carrying of in-ground tank during an earthquake
(target performance to satisfy the required performance shown in Table 3.1)

<table>
<thead>
<tr>
<th>Variation of performance</th>
<th>Performance level</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Seismic performance 1</td>
</tr>
<tr>
<td></td>
<td>[Sound]</td>
</tr>
<tr>
<td>Load-carrying capacity (deformation capacity)</td>
<td>-Displacement or deformation of the main structure during or after an earthquake*1 is small enough to meet the following conditions. -Change in storage capacity (volume inside the main structure) is minute enough to be practically ignored. -Neither liquid-tightness nor airtightness decreases for the membrane and roof.</td>
</tr>
<tr>
<td>Structural performance of in-ground tank</td>
<td>-No decrease in strength of the main structure after an earthquake</td>
</tr>
</tbody>
</table>

*1 Displacement or deformation of the main structure includes relative displacement between the side wall and the bottom slab, and the deformation of the circular crest of the side wall (radial deformation).

Table 3.3 Watertightness performance of in-ground tank during an earthquake
(target performance to satisfy the required performance shown in Table 3.1)

<table>
<thead>
<tr>
<th>Variation of performance</th>
<th>Performance level</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Seismic performance 1</td>
</tr>
<tr>
<td></td>
<td>[Sound]</td>
</tr>
<tr>
<td>Watertightness</td>
<td>-Post-earthquake inflow of surrounding groundwater into the main structure*1 is small enough to meet the following conditions. -No insulating capacity is deteriorated for the cold insulation layer contacting the inner surface of the main structure under conditions of appropriate control of water levels inside and outside the main structure, operation of the groundwater management system to maintain the water levels, and appropriate management of freezing temperature level.</td>
</tr>
<tr>
<td>Structural performance of in-ground tank</td>
<td></td>
</tr>
</tbody>
</table>

*1 The groundwater inflow into the main structure during an earthquake is allowed because it is small and has little effect on the insulation of the cold insulation layer since earthquakes act only for a limited time.
Table 3.4 Combinations of earthquake motion and seismic Performance level

<table>
<thead>
<tr>
<th>Seismic Performance level</th>
<th>Seismic Performance 1</th>
<th>Seismic Performance 2</th>
<th>Seismic Performance 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Level 1 earthquake motion</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Level 2L earthquake motion</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Level 2H earthquake motion</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

4. LOADINGS

In-ground tank structures are underground structures that are influenced by the very low temperature of LNG (162 °C). Loadings should be determined in view of these characteristics and the tank-specific conditions. The loadings to be used for verification purposes are determined separately for normal performance and for different levels of seismic performance.

4.1 Normal loading

The loads to be taken into account when verifying the normal performance of the walls of an in-ground tank are the weight of the walls themselves, earth pressure, internal gas pressure, liquid pressure, thermal loading, and roof load.

4.2 Determination of earthquake motion

Each earthquake motion to be used for verification is defined at the seismic basement and in terms of an acceleration response spectrum. A time-history waveform is set up so as to match the spectrum thus defined.

Level 1 earthquake motion is defined using a stochastic procedure, while Level 2 earthquake motion is defined using a deterministic procedure.

In this study, the service life is set at 50 years. For Level 1 earthquake motion, the acceleration at the seismic basement (2E) is defined as 230 gal based on the seismic hazard curve for the location, as shown in Table 4.1. The Level 2 earthquake motion is set using a simulated earthquake at 390 gal for Level 2L earthquake motion and at 620 gal for Level 2H (Table 4.2). The 620 gal motion is the value of the mean plus the standard deviation in view of the uncertainty involved in estimating the motion of the simulated earthquake. It is 1.6 times the Level 2L motion.

The simulated seismic waveform (artificial waveform) is designed to match the predetermined target response spectrum. For Level 1 earthquake motion, the simulated and observed waveforms are compared. Then, since the observed waveform is more severe on the structure than the simulated one here, the observed waveform is defined as the input earthquake motion.

The earthquake response in the nonlinear range should be taken into account. In this range, differences in waveform time history may have an impact on the nonlinear response even for an identical target spectrum. The guidelines recommend the use of multiple waveforms with different phase characteristics. In this case study, however, a seismic waveform with a certain phase characteristics is used for each level of earthquake motion.
Level 1 earthquake motion: Sodegaura waveform of the 1987 Chibaken-toho-oki earthquake, M6.7 (observed waveform)
Level 2L and 2H earthquake motions: La Union waveform of the 1985 Mexico earthquake, M8.1 (simulated waveform)

An earthquake generated by an active fault at the model location is estimated to yield a maximum acceleration of about 280 gal at the seismic basement, so this is included, within the Level 2 earthquake motion described above. However, this is not specifically discussed as the design earthquake motion.

The time-history waveforms and response spectra of the input earthquake motions are shown in Figures 4.1 and 4.2, respectively.

### 4.3 Effects of earthquake

The earthquake-induced loads induced by earthquakes listed in Table 4.3 are considered in this study. In the analysis by Method 3, separate analysis is carried out for normal loading and the sectional force acting on the main structure is calculated. Analysis at the time of an earthquake then treats this normal sectional force as the initial state.

#### Table 4.1 Definition of Level 1 earthquake motion (by stochastic procedure)

<table>
<thead>
<tr>
<th>Earthquake motion</th>
<th>Level 1 earthquake motion</th>
</tr>
</thead>
<tbody>
<tr>
<td>Probability of occurrence</td>
<td>Expected once or twice during the service life of the structure</td>
</tr>
<tr>
<td>Maximum acceleration at seismic basement</td>
<td>230gal</td>
</tr>
<tr>
<td>Return period</td>
<td>About 70 years</td>
</tr>
<tr>
<td>Probability of occurring once during the service life P (%) (reference value)*</td>
<td>About 50%</td>
</tr>
</tbody>
</table>

*The values in the table are for reference based on the assumption of a service life of 50 years. The following relation exists between recurrence interval T and probability of occurring once during the service life P (%): P/100 - 1 - (1 - 1/T) t where, t is the service life (in years)

#### Table 4.2 Definition of Level 2 earthquake motion (by deterministic procedure)

<table>
<thead>
<tr>
<th>Earthquake motion</th>
<th>Level 2L earthquake motion*</th>
<th>Level 2H earthquake motion**</th>
</tr>
</thead>
<tbody>
<tr>
<td>Probability of occurrence</td>
<td>Strong earthquake motion with a relatively small probability of occurrence during the service life of the structure</td>
<td>Very strong earthquake motion with an extremely small probability of occurrence during the service life of the structure</td>
</tr>
<tr>
<td>Typical earthquake</td>
<td>Minami-Kanto earthquake</td>
<td>Minami-Kanto earthquake</td>
</tr>
<tr>
<td>Type of earthquake</td>
<td>Large earthquake along the Sagami trough (reoccurrence of earthquake with motion equivalent to that of the Great Kanto Earthquake)</td>
<td>Large earthquake along the Sagami trough</td>
</tr>
<tr>
<td>Magnitude</td>
<td>M8</td>
<td>M8</td>
</tr>
<tr>
<td>Shortest distance to the fault</td>
<td>Horizontal 8km</td>
<td>8km</td>
</tr>
<tr>
<td></td>
<td>Vertical 17km</td>
<td>17km</td>
</tr>
<tr>
<td>Maximum acceleration at seismic basement 2E</td>
<td>390gal</td>
<td>620gal</td>
</tr>
<tr>
<td>Return period T</td>
<td>About 300 years</td>
<td>About 1,000 years</td>
</tr>
<tr>
<td>Probability of occurring once during the service life P (%) (reference value)**</td>
<td>About 15%</td>
<td>About 5%</td>
</tr>
</tbody>
</table>

*Level 2L earthquake motion: Level of earthquake motion generally expected at the site with occurrence of an M8-class earthquake
**Level 2H earthquake motion: motion expected at the site with occurrence of an M8-class earthquake
Upper limit is mean value plus 1 σ
*** Value calculated by the same method as in Table 4.1
5. ANALYSIS METHODS FOR VERIFICATION OF SEISMIC PERFORMANCE

In order to streamline the earthquake-resistant design of an in-ground tank, it is necessary to strictly evaluate the deformation capacity of the tank’s main structure. If the actual behavior of the structure can be accurately simulated, the deformation capacity and stress state of different parts of the structure can also be determined. As a result, a stricter verification can be carried out with the real limit state of the structure taken into consideration. Generally, for a three-dimensional structure such an in-ground tank, stricter analysis allows for more streamlined design than simple analysis. However, in cases where a sufficient amount of relevant data is available and well-proven performance is involved, a simple method may be adequate to meet the needs of analysis.

Two of the methods given in the guidelines are investigated in this study of seismic performance verification. The quasi-dynamic equivalent linear analysis method (Method 2) has a history of use in design and has proved effective in streamlining. The dynamic nonlinear analysis method (Method 3) is
expected to contribute to greater streamlining in the future through its greater sophistication.

5.1 Quasi-dynamic equivalent linear analysis (Method 2)

5.1.1 Analysis of earthquake response of soil
To calculate the relative displacement of the soil in the application of Method 2, an earthquake response analysis is carried out for soil. Table 5.1 shows the results of total stress analysis (equivalent linear analysis) under the influence of both Level 1 and Level 2 earthquake motions. For values of relative displacement used in analysis by Method 2 are those at the ground surface and at the base of the diaphragm wall, because in the model the diaphragm wall is integrated with the walls of the tank.

Table 5.1 Results of soil response analysis

<table>
<thead>
<tr>
<th>Earthquake motion</th>
<th>Level 1 Earthquake motion</th>
<th>Level 2L Earthquake motion</th>
<th>Level 2H Earthquake motion</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maximum acceleration at ground surface</td>
<td>319 gal</td>
<td>523 gal</td>
<td>699 gal</td>
</tr>
<tr>
<td>Maximum displacement at ground surface</td>
<td>5.9 cm</td>
<td>16.2 cm</td>
<td>31.7 cm</td>
</tr>
<tr>
<td>Maximum relative displacement between superstructure and substructure*</td>
<td>5.8 cm</td>
<td>15.8 cm</td>
<td>31.3 cm</td>
</tr>
</tbody>
</table>

* Relative displacement between ground surface and base of diaphragm wall

5.1.2 Structural analysis model

(1) Response displacement analysis model
Figure 5.1 shows the analysis model used. The model represents the tank walls and diaphragm walls as shells, while the surrounding ground, bearings, and interface between wall and diaphragm wall are treated as springs.

(2) Determination of soil spring value
The soil spring used in analysis by the response displacement method is modeled as an elastoplastic soil spring (Figure 5.2). The initial gradient of this soil spring is obtained using a finite element method. Specifically, a unit load is applied to a model of the soil containing no structure in the direction of the desired soil spring value. The resulting load-displacement relationship is then used to calculate the soil reaction force. The soil stiffness used in the analysis is the final value obtained by soil equivalent linear earthquake response analysis. The upper and lower limits of the soil spring reaction are chosen such that a uniform value is reached when the spring reaction reaches the active or passive earth pressure.

(3) Equivalent stiffness of structural members
The values of equivalent stiffness for the tank walls as used in Method 2 (quasi-dynamic equivalent linear analysis method) are shown in Table 5.2. The equivalent stiffness of the main structure is taken to be the residual stiffness at a point where some of the members suffer yielding of the reinforcement; this is obtained by iterative computations of sectional force and residual stiffness using a formula that reflect the effects of cracking.
5.2 Dynamic nonlinear analysis method (Method 3)

5.2.1 Dynamic coupled analysis model

The analysis model is shown in Figure 5.3. This is a coupled model of the soil and structure. The wall consists of three-dimensional shell elements, while the soil and bottom slab consist of solid elements. The bearing, and interface between wall and diaphragm wall are modeled as springs. The side and bottom boundaries of the analysis model are assumed to be viscous boundaries.

5.2.2 Model of soil mechanical properties

The physical properties of the soil used for dynamic analysis are assumed to be linear and equivalent to the ultimate physical properties of the soil based on earthquake response analysis of the soil. The values used in the analysis are listed in Table 5.3.

Note: Figures in the table indicate the ratio with respect to stiffness effective for the full face

Bending, axial, and shear stiffnesses are treated as uniform.
5.2.3 Model of structural member mechanical properties

(1) Outline of mechanical properties model
The in-ground LNG tank is subjected to three-dimensional analysis using general-purpose dynamic nonlinear analysis codes. In analyzing the wall and diaphragm wall of the in-ground tank, which are modeled with shell elements, the stiffness is determined with a subroutine.

The nonlinear property model of each member used to calculate stiffness consists of a history-dependent macro model reflecting reductions in stiffness due to flexural and axial forces in two directions, as well as the in-plane shear force (Table 5.4). The nonlinearity of the flexural and axial forces is assumed to be different in the vertical and circumferential directions. Thus an orthotropic model is assumed.

### Table 5.3 Physical properties of soil used in dynamic nonlinear analysis

<table>
<thead>
<tr>
<th>Depth Layer</th>
<th>Layer Thickness</th>
<th>Layer type</th>
<th>Unit weight kN/m³</th>
<th>Final stiffness ×10⁵ kN/m²</th>
<th>Damping Coefficient %</th>
</tr>
</thead>
<tbody>
<tr>
<td>14.00 - 9.35</td>
<td>4.65</td>
<td>Fill</td>
<td>18.0</td>
<td>48.4</td>
<td>6.7</td>
</tr>
<tr>
<td>9.35 - 4.70</td>
<td>4.65</td>
<td>Fill</td>
<td>18.0</td>
<td>24.1</td>
<td>17.6</td>
</tr>
<tr>
<td>4.70 - 0.20</td>
<td>4.90</td>
<td>Fill and landfill</td>
<td>19.0</td>
<td>15.2</td>
<td>22.6</td>
</tr>
<tr>
<td>-0.20 - 5.10</td>
<td>4.90</td>
<td>Landfill</td>
<td>18.0</td>
<td>9.5</td>
<td>20.5</td>
</tr>
<tr>
<td>-5.10 - -10.00</td>
<td>4.90</td>
<td></td>
<td>18.2</td>
<td>42.6</td>
<td>12.4</td>
</tr>
<tr>
<td>-10.00 - -14.90</td>
<td>4.90</td>
<td></td>
<td>17.0</td>
<td>37.6</td>
<td>10.9</td>
</tr>
<tr>
<td>-14.90 - -17.90</td>
<td>3.00</td>
<td></td>
<td>18.0</td>
<td>135.6</td>
<td>4.8</td>
</tr>
<tr>
<td>-17.90 - -19.80</td>
<td>1.90</td>
<td></td>
<td>18.0</td>
<td>135.6</td>
<td>4.9</td>
</tr>
<tr>
<td>-19.80 - -21.30</td>
<td>1.50</td>
<td>Diluvium</td>
<td>18.0</td>
<td>134.4</td>
<td>5.1</td>
</tr>
<tr>
<td>-21.30 - -26.10</td>
<td>4.80</td>
<td></td>
<td>18.0</td>
<td>131.6</td>
<td>5.4</td>
</tr>
<tr>
<td>-26.10 - -31.10</td>
<td>5.00</td>
<td></td>
<td>18.0</td>
<td>127.6</td>
<td>6.1</td>
</tr>
<tr>
<td>-31.10 - -36.10</td>
<td>5.00</td>
<td></td>
<td>18.0</td>
<td>124.8</td>
<td>6.5</td>
</tr>
<tr>
<td>-36.10 - -41.10</td>
<td>5.00</td>
<td></td>
<td>17.5</td>
<td>120.1</td>
<td>7.1</td>
</tr>
<tr>
<td>-41.10 - -48.05</td>
<td>6.95</td>
<td></td>
<td>17.5</td>
<td>145.2</td>
<td>8.8</td>
</tr>
<tr>
<td>-48.05 - -55.00</td>
<td>6.95</td>
<td></td>
<td>17.2</td>
<td>208.5</td>
<td>7.1</td>
</tr>
<tr>
<td>-55.00 - -59.80</td>
<td>4.80</td>
<td></td>
<td>17.0</td>
<td>234.8</td>
<td>6.5</td>
</tr>
<tr>
<td>-59.80 - -124.00</td>
<td>64.20</td>
<td></td>
<td>18.5</td>
<td>333.0</td>
<td>2.0</td>
</tr>
</tbody>
</table>

### Table 5.4 Concept of macro models of members

<table>
<thead>
<tr>
<th>Model for structural analysis</th>
<th>Macro model for calculating stiffness (subroutine)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Shell</td>
<td>Circumferential Flexural and axial forces</td>
</tr>
<tr>
<td>Vertical flexural and axial forces</td>
<td>In-plane shear</td>
</tr>
</tbody>
</table>

In-plane shear stiffness is determined based on the reinforcement strain calculated using a model of flexural and axial forces (Aoyagi's formula).
(2) Modeling of nonlinearity

The nonlinearity of members is modeled as a secant stiffness according to the presence of cracking, reinforcement yield, and member stress, as shown below. The stiffness used for structural analysis is tangential stiffness, so tangential stiffness is calculated by the subroutine based on the sectional force-strain relationship.

(i) Equations for calculating stiffness where no cracking occurs in concrete

Bending stiffness: \( EI_{\text{eff}} = E \cdot I_\varepsilon \)  
Axial stiffness: \( EA_{\text{eff}} = E \cdot A_\varepsilon \)  
In-plane shear stiffness: \( E_v = E \cdot A_\varepsilon /[2(1+\nu)] \)

(ii) Equations for calculating stiffness where flexural cracking occurs in concrete

The stress and strain in the reinforcement, as required to calculate stiffness, are obtained on the assumption that the reinforced concrete is behaving correctly based on the sectional force obtained by analysis.

Bending stiffness: \( EI_{\text{eff}} = E \cdot [(\sigma_{\text{acr}} / \sigma_s)^4 \cdot I_\varepsilon + \{1-(\sigma_{\text{acr}} / \sigma_s)^4\} \cdot I_\sigma] \)  
(5.4)

Axial stiffness: \( EA_{\text{eff}} = X_{\text{eff}} \cdot E \cdot A_\varepsilon / h \)  
In-plane shear stiffness: \( E_v = K \cdot A_\varepsilon / \varepsilon_{\text{efm}}\) (Aoyagi’s formula)  
(5.6)

(iii) Equations for calculating stiffness where cracking occurs throughout the cross section of concrete (full-face tension)

The strain in the reinforcement, as used to calculate stiffness, is obtained on the assumption that the reinforced concrete is behaving correctly based on the sectional force obtained by analysis.

Bending stiffness: \( EI_{\text{eff}} = M / \phi = M \cdot L / (\varepsilon_{\text{sm1}} - \varepsilon_{\text{sm2}}) \)  
(5.7)

Axial stiffness: \( EA_{\text{eff}} = N / \varepsilon_{\text{sm}} \)  
(5.8)

In-plane shear stiffness: \( E_v = K \cdot A_\varepsilon / \varepsilon_{\text{efm}}\) (Aoyagi’s formula)  
(5.9)

(iv) Out-of-plane shear stiffness

For the out-of-plane shear stiffness, an equivalent stiffness based on an assumption of proportionality to axial stiffness is used, where

- \( E \): Young’s modulus of concrete
- \( I_{\text{eff}} \): Effective moment of inertia
- \( A_{\text{eff}} \): Effective sectional area
- \( I_\varepsilon \): Gross section equivalent moment of inertia
- \( A_\varepsilon \): Gross section equivalent sectional area
- \( \nu \): Poisson’s ratio
- \( I_\sigma \): Moment of inertia with concrete in tension being ignored
- \( \sigma_s \): Reinforcement stress
- \( \sigma_{\text{acr}} \): Reinforcement stress at the time of (immediately after) cracking
- \( X_{\text{eff}} \): Equivalent height of neutral axis corresponding to \( I_{\text{eff}} \)
- \( h \): Height of member
- \( K \): Constant (360 t/m²)
(3) Hysteresis behavior of mechanical property model

The mechanical property model of a member basically exhibits the hysteresis behavior described below.

(i) Before cracking
- The sectional force depends on the initial stiffness.

(ii) After cracking occurs
- The hysteresis point moves to the points determined by the equations for stiffness during loading. For the flexural and axial forces, the hysteresis point moves to, the points determined by the equations for stiffness according to whether the hysteresis point is in a state of gross sectional compression, the flexural cracking occurs in concrete, or the hysteresis point is in the gross section tension.
- Bending stiffness is assumed to be asymmetrical depending on whether the curvature is positive or negative, in view of the difference in the amount of reinforcement on the inside and outside of the cross section.
- An origin-oriented model is assumed where the hysteresis point moves toward the origin during unloading.

(iii) After reinforcement yield
- The hysteresis point follows a path of a tangential stiffness equivalent to 1% of the gross section stiffness (initial stiffness). The reinforcement yield point is defined as a point where any of the reinforcing bars first yields.

Figure 5.4 shows a hysteresis loop representing the relationship between the in-plane shear force and shear strain.

Figure 5.4 Hysteresis loop of in-plane shear and shear strain
6. CHECK INDEXES AND LIMIT VALUES FOR SEISMIC PERFORMANCE

To verify the performance of an in-ground tank, it is necessary to define suitable check indexes and also limit values of the check indexes for judgment of whether target performance can be achieved. The task is then to ascertain that the response of the structure to the design loads does not reach the chosen limit values.

The check indexes used to judge the seismic performance of the main tank structure are defined according to individual analysis methods used for the verification, since different response values are calculated for different methods. Tables 6.1, 6.2, and 6.3 list the limit values [6] of indexes used for verification of the structural performance of the main tank structure during an earthquake.

In verifying structural performance during an earthquake, limit values are established for verification of load-carrying capacity so as to ensure that the in-ground tank is able to retain the desired level of performance after the earthquake. To identify load-carrying performance, the strength and deformation capacity of the wall, the relative displacement between the wall and the bottom slab, and the deformation of the uppermost part of the wall are checked. There is no verification of watertightness because the groundwater level around the in-ground tank is to be lowered.

Method 3 is unable to directly confirm seismic performance Level 3 by calculation, which requires that the main structure never suffers failure in an earthquake. In this case study, therefore, the load-carrying capacity of the main structure is checked at the element level on the premise that structures such as in-ground tanks never fail as long as they pass element-level verification.

For limit values, the deformation that corresponds to the maximum strength is defined for seismic performance Level 2. For seismic performance Level 3, deformation similar to that for seismic performance Level 2 is defined as the limit value to ensure design on the safe side. Different safety factors are, however, defined for seismic performance Levels 2 and 3.

6.1 Check indexes and limit values for seismic performance where Method 2 is used

6.1.1 Check indexes for seismic performance level 1 against Level 1 earthquake motion

(1) Verification of load-carrying capacity

1) Verification of strength of main structure
   a. Verification of cross-sectional strength against flexural, axial, and in-plane shear forces
      To simplify the verification, the in-plane shear force is converted into an axial force and then the check is carried out for flexural and axial forces. The design bending moment \( M_d \) is assumed to be equal to or less than the design flexural strength due to yielding \( M_{yd} \).
      \[
      \gamma_i \cdot M_d / M_{yd} \leq 1.0
      \]
      (6.1)
   b. Verification of cross-sectional strength against out-of-plane shear force
      The design shear force is assumed to be equal to or less than the design shear force of the member \( V_{yd} \).
2) Relative displacement of the tank wall and bottom slab and deformation of the uppermost part of the wall
The membrane and roof fully meet the target performance for liquid-tightness and airtightness. Verification is omitted because seismic performance Level 2 is checked.

(2) Verification of watertightness
The main structure of the in-ground tank fully meets the target performance for watertightness because the main structure of the in-ground LNG tank remains within the elastic range. Verification is therefore omitted.

Table 6.1. Limit values for verification of load-carrying performance (Seismic performance Level 1)

<table>
<thead>
<tr>
<th>Target performance</th>
<th>Seismic performance Level 1 (tank is sound)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Main structure maintains its strength after earthquake</td>
</tr>
<tr>
<td>Method 2</td>
<td>-Sectional forces during an earthquake less than load-carrying capacity</td>
</tr>
</tbody>
</table>

6.1.2 Check indexes and limit values for seismic performance levels 2 and 3 against level 2 earthquake motions

(1) Verification of load-carrying capacity

1) Verification of strength of main structure
The verification methods for flexural and axial forces, in-plane shear force, and out-of-plane shear force are similar to those for seismic performance Level 1, so the explanation of verification is omitted.

2) Verification of relative displacement between tank wall and bottom slab
The relative displacement at the point where the tank wall meets the bottom slab is assumed to be less than the allowable displacement of the membrane as determined from the effects of repetitive loading and unloading during overhaul inspections or while the tank is filled and emptied.

\[ \gamma_i \cdot \frac{\delta_{rbd}}{\delta_{bd}} \leq 1.0 \quad (6.2) \]

where

- \( \delta_{rbd} \): Relative displacement at point where tank wall meets bottom slab
- \( \delta_{bd} \): Allowable displacement; 45 mm (in the radial direction)

Allowable displacement where the slab (equipment for absorbing relative displacement) is installed between the wall of the tank and the bottom slab, which is set at 45 mm
3) Verification of deformation at the uppermost part of the wall

The rim deformation (oval deformation) of the uppermost part of the wall is assumed to be less than the limit value determined by the deformation capacity of the roof.

\[ \gamma_b \cdot \frac{\delta_{nd}}{\delta_{id}} \leq 1.0 \]  

where

- \( \delta_{nd} \): Radial relative displacement at uppermost part of the wall in the range from 0° to 180°
- \( \delta_{id} \): Limit value determined by deformation capacity of the roof; 8.7 cm

In this case study, the limit value is set at 1/800 of the roof diameter (so the stress of the steel roof remains below its yield strength)

\( \gamma_b \): Member factor

(2) Verification of watertightness

Verification is omitted because the main structure of the in-ground tank is not required to be watertight. The groundwater level around the tank is assumed to have been lowered so as to avoid problems with watertightness.

### Table 6.2 Limit values for verification of load-carrying Performance (Seismic performance Level 2)

<table>
<thead>
<tr>
<th>Target performance</th>
<th>Seismic performance Level 2 (tank remains functional)</th>
<th>Change in liquid storage capacity is less than the level causing LNG outflow</th>
<th>No substantial deterioration occurs in the liquid-tightness of the membrane and in the airtightness of the roof</th>
</tr>
</thead>
</table>
| Method 2           | -Sectional forces during earthquake are less than load-carrying capacity  
|                    | -Ultimate sectional strength against bending and axial forces  
|                    | -Out-of-plane shear strength  
|                    | -In-Plane shear strength  
|                   | -The allowable deformation of the roof is small enough to allow verification to be omitted |
| Method 3           | -Compressive strain of element less than ultimate compressive strain of concrete (\( \varepsilon'_{cu} : 3500 \mu \))  
|                    | -Tensile strain of element less than allowable strain (14000 \( \mu \)) determined by the fatigue limit of membrane  
|                    | -Out of plane shear force during earthquake less than load-carrying capacity  
|                   | -Relative displacement at the interface between wall and bottom slab less than allowable deformation (45mm: radial direction) determined by the fatigue limit)*  
|                   | -Oval deformation of the wall rim less than allowable deformation (1/800 of roof diameter)  

* Allowable deformation is the limit value for a case in which the slab (equipment for absorbing relative displacement) is used. In this case study, the relative displacement is assured to be no more than 45mm.
Table 6.3 Limit values for verification of the load-carrying performance (Seismic Performance Level 3)

<table>
<thead>
<tr>
<th>Seismic Performance Level 3 tank never collapse (no liquid leaks)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Target performance</td>
</tr>
<tr>
<td>The main structure maintains its strength after earthquake</td>
</tr>
<tr>
<td>Change in liquid storage capacity is within the allowable range and</td>
</tr>
<tr>
<td>Deterioration in liquid-tightness and airtightness of the membrane and in the airtightness of the roof is less than the allowable level</td>
</tr>
</tbody>
</table>

Method 2

- Sectional forces during earthquake less than load-carrying capacity
  - Ultimate sectional strength against bending and axial forces
  - Out-of-plane shear strength
  - In-Plane shear strength
- The allowable deformation of the roof is small enough to allow verification to be omitted
- Relative displacement at the interface between wall and bottom slab less than allowable deformation (45mm: radial direction) determined by the fatigue limit*

Method 3

- Compressive strain of element less than ultimate compressive strain of concrete ($\varepsilon'_{cu}: 3500 \mu$)
- Tensile strain of element less than allowable strain (14000 $\mu$) determined by the fatigue limit of membrane
- Out-of-plane shear force during earthquake less than load-carrying capacity
- Relative displacement at the interface between wall and bottom slab less than allowable deformation (45mm: radial direction)
- Oval deformation of the wall rim less than allowable deformation (1/800 of roof diameter)

*Allowable deformation is the limit value for a case in which the slab (equipment for absorbing relative displacement) is used. In this case study, the relative displacement is assured to be no more than 45mm.

6.2 Check indexes and limit values for seismic performance where Method 3 is used

6.2.1 Check indexes and limit values for seismic performance level 1 against level 1 earthquake motion

Verification is omitted because the verification for seismic performance level 1 against Level 1 earthquake motion using Method 2 can be used as an alternative.

6.2.2 Check indexes and limit values for seismic performance level 2 and 3 against Level 2 earthquake motions

(1) Verification of load-carrying capacity

1) Verification of deformation capacity of main structure of in-ground tank

a. Verification of compressive strain of concrete

It is confirmed whether or not the compressive principal strain of an element is below the limit value of compressive strain of concrete.

$$\gamma_i \cdot \varepsilon'_{rd} / \varepsilon'_{cd} \leq 1.0$$  \hspace{1cm} (6.5)

where

- $\varepsilon'_{rd}$: Compressive principal strain of element
- $\varepsilon'_{cd}$: $\varepsilon'_{cu} / \gamma_b$
- $\varepsilon'_{cu}$: Limit value of compressive strain of concrete (Ultimate compressive strain: 3500 $\mu$)
- $\gamma_b$: Member factor
b. Verification of tensile strain of element
It is confirmed whether or not the tensile principal strain of an element is below the allowable strain determined by the fatigue limit.
\[
\gamma_i \cdot \frac{\varepsilon'_{td} / \varepsilon'_{le}}{\varepsilon'_{le}} \leq 1.0
\]  
(6.6)

where
\[
\varepsilon'_{td} : \text{Tensile principal strain of element}
\]
\[
\varepsilon'_{le} : \text{Limit value of tensile axial strain of element: 14,000 \mu}
\]
Allowable strain confirmed by membrane deformation test by repetitive loading and unloading: set at 14,000 \mu in this case study
\[
\gamma_b : \text{Member factor}
\]

2) Verification cross-sectional strength against out-of-plane shear force
The design shear force \(V_d\) is set equal to or lower than the design shear force of the member \(V_{td}\).
\[
\gamma_i \cdot \frac{V_d}{V_{td}} \leq 1.0
\]  
(6.7)

3) Verification of relative displacement between tank wall and bottom slab, and deformation of uppermost part of the wall
Verification is omitted because it is similar to the verification by Method 2 for seismic performance.

(2) Verification of watertightness
Verification is omitted because the main structure of the in-ground tank is not required to be watertight, as already mentioned.

7. SAFETY FACTORS
The safety factors that are used in normal and seismic performance checks are the following: material factor, member factor, load factor, structural analysis factor, and structure factor. These safety factors must be determined in view of such variability as undesirable changes in the characteristic values of materials used and in expected loads, uncertainties associated with structural analysis, calculation, or the determination of limit values, and the importance of the tank concerned.

7.1 Safety factors for Method 2
Table 7.1 lists the safety factors adopted for verification of the strength of the tank wall when using Method 2. The factors were established based on "A study on rationalization of design of reinforced concrete in-ground LNG tanks"[3] as described below. The safety factors used for verification of the relative displacement between the tank wall and the bottom slab, and the deformation of the uppermost part of the wall are described in the section related to safety factors for Method 3.

(i) Characteristic values of materials and material factors
The characteristic value of the reinforcement is set at 370 N/mm², 5% higher than the standard value of 350 N/mm², for an earthquake of Level 2H motion. This is a level of motion rarely encountered. The value is based on statistical analysis of materials data obtained in tests on similar construction work where quality control was excellent. For earthquakes other than Level 2H motion, existing standard values as given in the Standard Specifications for Reinforced Concrete are used without modification to ensure safety because there is no guarantee of the characteristic values obtained in tests being
reproduced for concrete strength. For the material factors, the standard values given in the Standard Specifications are used.

(ii) Member factors
The structural members of an in-ground tank are 2 to 6 m thick, so the effects of dimensional errors on cross-sectional strength can be safely ignored (though for some members, the effect ranges from 5% to 10%). In view of this, some of the member factors are set below the standard values given in the Standard Specifications for Reinforced Concrete. The degree of reduction varies according to the performance level that is to be guaranteed by the limit state.

For shear strength against Level 2 earthquake motion, a value larger than the flexural and axial forces is set according to the Standard Specifications for Reinforced Concrete to increase the ductility of the member.

(iii) Load factors
All seismic load factors are set at 1.0 because uncertainty is already taken into account when determining the characteristic values of earthquake load and because the probability of different loads occurring at the same time is low.

<table>
<thead>
<tr>
<th>Earthquake motion</th>
<th>Level 1</th>
<th>Level 2L</th>
<th>Level 2H</th>
</tr>
</thead>
<tbody>
<tr>
<td>Performance level</td>
<td>Seismic performance Level 1</td>
<td>Seismic performance Level 2</td>
<td>Seismic performance Level 3</td>
</tr>
<tr>
<td>Check index</td>
<td>Sectional force</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Material factor $\gamma_m$</td>
<td>Concrete $\gamma_m$</td>
<td>1.3</td>
<td>1.3</td>
</tr>
<tr>
<td>Reinforcement $\gamma_m$</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Member factor $\gamma_b$</td>
<td>Bending and Axial forces $\gamma_b$</td>
<td>Bending force is predominant</td>
<td>1.1</td>
</tr>
<tr>
<td>Out-of-plane Shear $\gamma_b$</td>
<td>Concrete</td>
<td>1.3</td>
<td>1.55</td>
</tr>
<tr>
<td>Reinforcement $\gamma_b$</td>
<td>1.15</td>
<td>1.4</td>
<td>1.35</td>
</tr>
<tr>
<td>Load factor $\gamma_s$</td>
<td>Self weight</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Incremental earth pressure due to filling</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Normal unsymmetrical pressure</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Unsymmetrical pressure due to filling for disaster control</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Gas Pressure</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Liquid Pressure</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Thermal load</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Roof load during an earthquake</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Inertia force of the main structure</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Dynamic liquid pressure</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Response displacement (Level 1)</td>
<td>1.0</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Response displacement (Level 2L)</td>
<td>-</td>
<td>1.0</td>
<td>-</td>
</tr>
<tr>
<td>Response displacement (Level 2H)</td>
<td>-</td>
<td>-</td>
<td>1.0</td>
</tr>
<tr>
<td>Structural analysis factor $\gamma_a$</td>
<td>General load</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Thermal load</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Load during an earthquake</td>
<td>1.1</td>
<td>1.1</td>
<td>1.0</td>
</tr>
<tr>
<td>Structure factor $\gamma_i$</td>
<td>1.1</td>
<td>1.05</td>
<td>1.0</td>
</tr>
</tbody>
</table>

Note: The table lists safety factors for a tank filled with LNG and subjected to thermal loading.
(iv) Structural analysis factors
For verification by Method 2, the structural analysis factor for the tank wall during an earthquake is set at 1.1, because uncertainty is involved in the equivalent linear analysis used to approximate the nonlinear characteristics of members and in the evaluation of ground reaction using a spring model. For verification of seismic performance Level 3, the structural analysis factor is set at 1.0 considering the low probability of Level 2H earthquake motion occurring.

(v) Structure factors
The importance of an in-ground LNG tank in the limit state is evaluated in terms of the impact of damage on society, its effect on the functioning of the facility, the difficulty of repair or restoration, the need to predict irregularities, and vulnerability to loading. Consequently, the selected structure factors range from 1.1 during Level 1 earthquake motion to 1.0 during Level 2H earthquake motion, according to the limit state.

7.2 Safe Factors for Method 3

The check indexes used for Method 3 consist of not only the conventional sectional forces but also indexes related to deformation of the main structure, such as the compressive strain and tensile strain of elements. Consequently, safety factors are also established for these additional check indexes. Tables 7.2 and 7.3 show the safety factors used for verification by Method 3. The safety factors used to verify seismic performance Levels 2 and 3 by Method 3 are determined based on the principles outlined below.

(i) Characteristic values of materials and material factors
The characteristic value of the reinforcement is set at -370 N/mm² against Level 2H earthquake motion, as for Method 2. For the material factors, the standard values given in the Standard Specifications are used.

(ii) Member factors
-Compressive strain and tensile strain of elements
  The member factors related to element strain are set at the same level as the flexural and axial forces for Method 2. They are set at 1.1 for seismic performance Level 2, and 1.05 for seismic performance Level 3.

-Relative displacement between tank wall and bottom slab, and deformation of the uppermost part of the wall
  The limit values of the relative displacement between the tank wall and the bottom slab, and of deformation of the uppermost part of the wall are determined by deformation capacities of the membrane and roof. The limit values are determined to provide some redundancy, so the member factors are set at 1.0.

-Member factors for out-of-plane shear force
  The member factor for the out-of-plane shear strength against Level 2 earthquake motion is set at a value larger than the flexural and axial forces according to the Standard Specification for Reinforced Concrete to increase the ductility of the member.
(iii) Load factors
All of the seismic load factors are set at 1.0 as for Method 2.

(iv) Structural analysis factors
The structural analysis factors are set at 1.2 in view of the uncertainty involved in the nonlinear structural analysis model. For verification of seismic performance Level 3, the structural analysis factors are set at 1.0 as for Method 2 in view of the low probability of Level 2H earthquake motion occurring.

(v) Structure factors
The structure factors are set as for Method 2 because they are determined based on the importance of the in-ground LNG tank and do not depend on the analysis method.

Table 7.2 Safety factors for Method 3 (Seismic Performance Level 2)

<table>
<thead>
<tr>
<th>Performance level</th>
<th>Compressive strain of element</th>
<th>Tensile strain of element</th>
<th>Out-of-plane shear strength</th>
<th>Relative displacement between wall and slab</th>
<th>Radial deformation of wall rim</th>
</tr>
</thead>
<tbody>
<tr>
<td>Concrete</td>
<td>1.3</td>
<td>1.3</td>
<td>1.3</td>
<td>1.3</td>
<td>1.3</td>
</tr>
<tr>
<td>Reinforcement</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Deformation of structure</td>
<td>1.1</td>
<td>1.1</td>
<td>-</td>
<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Load factor $\gamma_f$</td>
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<td>1.0</td>
<td>1.0</td>
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</tr>
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Table 7.3 Safety factors for Method 3 (Seismic Performance Level 3)

<table>
<thead>
<tr>
<th>Performance level</th>
<th>Compressive strain of element</th>
<th>Tensile strain of element</th>
<th>Out-of-plane shear strength</th>
<th>Relative displacement between wall and slab</th>
<th>Radial deformation of wall rim</th>
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</thead>
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<tr>
<td>Concrete</td>
<td>1.3</td>
<td>1.3</td>
<td>1.3</td>
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<td>Reinforcement</td>
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<td>1.0</td>
<td>1.0</td>
</tr>
<tr>
<td>Deformation of structure</td>
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<td>1.2</td>
<td>-</td>
<td>1.2</td>
<td>1.2</td>
</tr>
<tr>
<td>Load factor $\gamma_f$</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
<td>1.0</td>
</tr>
</tbody>
</table>

8. VERIFICATION OF SEISMIC PERFORMANCE LEVEL 1 AGAINST LEVEL 1 EARTHQUAKE MOTION

8.1 Verification of seismic performance level 1 by Method 2
8.1.1 Sectional forces
The sectional forces generated by level 1 earthquake motion are shown in Figure 8.1. The figure shows the sectional forces in the $135^\circ$ range in the cross section that are severe on vertical reinforcement, and the sectional forces in the $180^\circ$ range in the cross section (on the loading side) that are severe on the circumferential reinforcement in the lowermost part.

8.1.2 Verification of load-cycling capacity

(1) Verification of strength of the main structure

1) Verification of cross-sectional strength against flexural and axial forces and in-plane shear forces
The reinforcement arrangement based on the sectional forces generated by Level 1 earthquake motion shown in Figure 8.1 is shown in Figure 8.2 (solid line). Based on the reinforcement arrangement, the parts with the largest amount of reinforcement are checked. The results are shown in Table 8.1. In-plane shear forces are converted to axial forces for verification. The standards are met in all the cross sections.

2) Verification of cross-sectional strength against out-of-plane shear forces
Verification for out-of-plane forces is omitted because the amount of shear reinforcement is determined for Level 2 earthquake motions that apply heavy loading.

Legend: Positive bending moment: Tension on the outside Positive axial force: Tensile force

Figure 8.1 Sectional forces in wall (Level 1 earthquake motion)
Figure 8.2 Amounts of reinforcement determined for Methods 2 and 3 (main reinforcement)

Table 8.1 Verification of cross-sectional strength against flexural and axial forces and in-plane shear force

<table>
<thead>
<tr>
<th>Cross section</th>
<th>Vertical direction AP-12.0 m 135° range</th>
<th>Circumferential direction AP-19.8 m 180° range</th>
<th>Remarks</th>
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</thead>
<tbody>
<tr>
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<td>100</td>
<td></td>
</tr>
<tr>
<td>Height H (cm)</td>
<td>180</td>
<td>180</td>
<td></td>
</tr>
<tr>
<td>Sectional forces acting in the cross section</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>M_d (kN/m/m)</td>
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<td>-984</td>
<td>γ_d = 1.1</td>
</tr>
<tr>
<td>N_d (kN/m)</td>
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<td>5,329</td>
<td>γ_d = 1.1</td>
</tr>
<tr>
<td>Outside reinforcement</td>
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<td></td>
<td></td>
</tr>
<tr>
<td>d_1 (cm)</td>
<td>18.0</td>
<td>33.0</td>
<td></td>
</tr>
<tr>
<td>A_s1 (cm^2/m)</td>
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<td>D29@300 21.4</td>
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<tr>
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<td></td>
<td></td>
</tr>
<tr>
<td>d_2 (cm)</td>
<td>166.0</td>
<td>151.0</td>
<td></td>
</tr>
<tr>
<td>A_s2 (cm^2/m)</td>
<td>D38@300 38.0</td>
<td>D38@300 38.0</td>
<td></td>
</tr>
<tr>
<td>M_yd (kN/m/m)</td>
<td>-870</td>
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<td>-3,610</td>
<td>-6,506</td>
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<tr>
<td>γ_y · M_d / M_yd</td>
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<td>γ_y = 1.1</td>
</tr>
<tr>
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<td>OK</td>
<td></td>
</tr>
</tbody>
</table>

* Including in-plane shear force  Positive axial force: Tension  Negative bending moment: Inward bending

(2) Verification of relative displacement of the wall of the tank and the bottom slab and deformation of the uppermost part of the wall.
Verifications are omitted because the liquid-tightness and airtightness of the membrane and the roof fully achieve the target performance as the main structure of the in-ground LNG tank behaves in the elastic range, and because seismic performance level 2 is checked.

8.2 Verification of seismic performance level 1 by Method 3
Verification is omitted because the verification for seismic performance level 1 by Method 2 can be used as an alternative.
9. VERIFICATION OF SEISMIC PERFORMANCE LEVEL 3 AGAINST LEVEL 2 EARTHQUAKE MOTION

The verification of seismic performance Level 2 is omitted because the Level 3 verification uses the same check indexes and limit values, and is carried out for the stronger for Level 2H earthquake motion.

9.1 verification of seismic performance Level 3 by Method 2

9.1.1 Sectional forces

The sectional forces generated by Level 2H earthquake motion are shown in Figure 9.1. This demonstrates that severe sectional forces in the $135^\circ$ range act on the vertical reinforcement, while severe sectional forces in the $180^\circ$ range act in the cross section (on the loading side) on the circumferential reinforcement in the lowermost part. These sectional forces generated by Level 2H earthquake motion are greater than those caused by Level 1 earthquake motion. For example, the in-plane shear force is about 1.5 times larger.

Figure 9.1 Sectional forces in the wall (Level 2H earthquake motion)
9.1.2 Verification of load-carrying capacity

(1) Verification of cross-sectional strength

1) Verification of cross-sectional strength against flexural and axial forces and in-plane shear force
A reinforcement arrangement designed on the basis of the sectional forces generated by the Level 2H earthquake motion shown in Figure 9.1 is illustrated in Figure 8.2(dotted line). The sectional forces are greater than those generated by Level 1 earthquake motion, so the amount of reinforcement is approximately 400 t greater than in the case of a design for Level 1 earthquake motion. Based on this reinforcement arrangement, the parts with the greatest quantity of reinforcement are checked. The results are shown in Table 9.1. The in-plane shear forces are converted to axial forces for verification purposes. The standards are met in all cross sections.

2) Verification of cross-sectional strength against out-of-plane shear forces
Reinforcement is arranged as shown in Figure 9.2(dotted line) based on the sectional forces generated by the Level 2H earthquake motion shown in Figure 9.1. The results of checking the cross-sectional strength at the base of the wall are shown in Table 9.2. The standards are met.

(2) Verification of relative displacement between tank wall and bottom slab
The relative displacement (1.4 cm) of the tank wall with respect to the bottom slab is below the limit value (4.5 cm). Thus, the joint between the wall and the bottom slab is considered to have the desired deformational capacity.

Table 9.1 Verification of cross-sectional strength against flexural and axial forces and in-plane shear force

<table>
<thead>
<tr>
<th>Cross section</th>
<th>Vertical direction</th>
<th>Circumferential direction</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
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<td>100</td>
</tr>
<tr>
<td></td>
<td>Height H (cm)</td>
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<td>180</td>
</tr>
<tr>
<td></td>
<td>Sectional forces acting in the cross section</td>
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</tr>
<tr>
<td></td>
<td>$M_d$ (kN·m/m)</td>
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<td>-837</td>
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<td>$d_1$ (cm)</td>
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</tr>
<tr>
<td></td>
<td>$A_{s1}$ (cm$^2$/m)</td>
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<td>D35@300 26.5</td>
</tr>
<tr>
<td></td>
<td>Inside reinforcement</td>
<td>$d_2$ (cm)</td>
<td>166.0</td>
</tr>
<tr>
<td></td>
<td>$A_{s2}$ (cm$^2$/m)</td>
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<td>D35@300 31.9</td>
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<td>$M_{ad}$ (kN·m/m)</td>
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<td>-927</td>
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<td>$\gamma_s \cdot M_d / M_{ad}$</td>
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*Including in-plane shear force
Positive axial force: Tension Negative bending moment: Inward bending
Table 9.2 Verification of cross-sectional strength against out-plane shear force

<table>
<thead>
<tr>
<th>Cross section</th>
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<th>Circumferential direction</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Width B (cm)</td>
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<td>100</td>
<td></td>
</tr>
<tr>
<td>Height H (cm)</td>
<td>180</td>
<td>180</td>
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<tr>
<td>Sectional forces acting in the cross section</td>
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</tr>
<tr>
<td>$M_a$ (kN·m/m)</td>
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<td>$V_a$ (kN/m)</td>
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<td>12</td>
<td>$\gamma_s = 1.0$</td>
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<td>Outside reinforcement</td>
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<td></td>
<td></td>
</tr>
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<td>$d_1$ (cm)</td>
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<td>33.0</td>
<td>14.2</td>
</tr>
<tr>
<td>$A_{s,1}$ (cm²/m)</td>
<td>D35@300 31.9</td>
<td>D32@300 26.5</td>
<td>D41@300 44.7</td>
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<tr>
<td>Inside reinforcement</td>
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<td></td>
</tr>
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<td>$d_2$ (cm)</td>
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<td>136.0</td>
</tr>
<tr>
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<td>D35@300 31.9</td>
<td>D32@300 26.5</td>
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<td>Shear reinforcement</td>
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<td>10.6</td>
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<td>$S$ (cm)</td>
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<td>60.0</td>
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<tr>
<td></td>
<td>$V_{a,td}$ (kN/m)</td>
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<td>0</td>
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<td></td>
<td>$V_{a,td}$ (kN/m)</td>
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<td>18</td>
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<td></td>
<td>$V_{a,td}$ (kN/m)</td>
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<td>18</td>
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<tr>
<td></td>
<td>$\gamma_V \cdot V_{a,td} / V_{a,td}$</td>
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</tbody>
</table>

* Including in-plane shear force  Positive axial force: Tension  Negative bending moment: Inward bending

(3) Verification of deformation of the uppermost part of the wall
The deformation (6.2 cm) of the uppermost part of the wall is below the limit value (8.7 cm) for verification as determined from the deformation capacity of the roof. The main structure is, therefore, considered to have the desired deformation capacity.

9.2 Verification of seismic performance level 3 by Method 3

For analysis by Method 3, a model is constructed with the reinforcement arrangement determined for Level 1 earthquake motion. The input earthquake motion used for this analysis is the data obtained during a five-second interval from 9.0 to 14.0 seconds (Figure 4.1) during which the stress on the structure reaches a maximum.

9.2.1 Response values of structural members
(1) Deformation mode of in-ground LNG tank
The stress on the in-ground tank reaches a maximum at the point when the relative displacement between the uppermost and lowermost extremities of the wall becomes largest. The time history waveforms in the free field and of relative displacement between the uppermost and lowermost extremities of the wall are shown in Figure 9.3 for the case of Level 2 motion. The maximum relative displacement of the wall is about 18 cm. Method 3 is able to track the increasing deformation of elements once the reinforcement has yielded, so the relative displacement exceeds the maximum value found by Method 2 by about 6 cm. The relative displacement reaches this maximum value after 3.8 seconds, which is the same time frame as the maximum in analysis by the response displacement method.

The mode of deformation of both ground and wall at the point of maximum relative deformation (3.8 seconds) is shown in Figure 9.4. The wall deforms in the shear mode, corresponding to the deformation of the ground.

The free field relative displacement (relative displacement between the base of the wall and the ground surface) is about 26 cm. In a pushover analysis [6] of an in-ground tank wall, the wall displacement had to exceed 60 cm for the stress on the in-ground tank to reach a maximum for a reinforcement ratio of 1% or less. The reinforcement ratio of the in-ground tank in this case study is 1% or less in most areas, so the deformation capacity of the tank exceeds the relative displacement of the ground. The tank is, therefore, unlikely to collapse during an earthquake.

---

**Figure 9.3 Time history response of free field and wall**

**Figure 9.4 Distribution of displacements of free field and wall (at 3.8 seconds)**

**Figure 9.5 Sectional forces governing element stress**
(2) Sectional forces governing the response of elements
The sectional forces that govern element stress are determined before verification of the deformation capacity of each element. The sectional forces predominant in each element are extracted based on the sectional forces at the time when the reinforcement yields. The results are listed in Figure 9.5.

In the main structure of the in-ground tank, the predominant forces are in-plane shear force and circumferential axial force. The predominance of in-plane shear force in the $45^\circ$ to $135^\circ$ range in the wall corresponds to the fact that the wall is in shear deformation mode. The analysis model does not take into account delamination or sliding of the ground and the structure, so the wall deforms in line with displacement of the ground as a result of circumferential tension near the ground surface (near the uppermost extremity of the wall). This is where the displacement response of the ground reaches a maximum. The circumferential tension is, therefore, predominant. In-plane shear force is a predominant sectional force throughout the wall.

**9.2.2 Verification of load-carrying capacity**

(1) Verification of load-carrying capacity
As the sectional forces governing the response of wall elements, the in-plane shear force at the center of the wall is extracted in the $45^\circ$ to $135^\circ$ range, and the axial force and bending moment are found for the loading and unloading side of the wall (Figure 9.5). For verification of the deformation capacity of each element against the sectional forces, compressive and tensile principal strains (response values) are calculated for comparison with the limit values of element strain.

1) Verification of deformation capacity of main structure
a. Verification of compressive strain of concrete
The distribution of maximum compressive principal strain inside and outside the wall is shown in Figure 9.6. The compressive principal strain exceeds $1500 \mu$ in the range $45^\circ$ to $135^\circ$ in the wall, where in-plane shear force is predominant. The time history waveform of compressive principal strain for elements that experience the maximum compressive principal strain ($67.5^\circ$ AP-7.6 m) is shown in Figure 9.7. The compressive principal strain is below the limit value for verification of concrete compressive strain (3300 $\mu$). Thus, it is assumed that no members (elements) suffer compressive failure.

b. Verification of tensile strain of elements
For verification of the tensile strain in the area where the membrane is installed, the maximum tensile principal strain inside the wall is determined. The distribution of maximum tensile principal strain of the wall is shown in Figure 9.8. Tensile principal strain is predominant at the uppermost extremity of the wall on the loading and unloading sides and at the center of the wall in the $45^\circ$ to $135^\circ$ range, which corresponds to the area where circumferential axial tensile force and in-plane shear force are predominant, as shown in Figure 9.5. The time history waveform of tensile principal strain for elements that experience the maximum compressive principal strain ($22.5^\circ$ AP+15.3 m) is shown in Figure 9.9. The tensile principal strain is below the limit value for verification of strain (13,300 $\mu$) determined from the fatigue limit of the membrane. Thus, the members (elements) are assumed to have the desired deformation capacity.

2) Verification of cross-sectional strength against out-of-plane shear forces
The layout of reinforcement based on the sectional forces generated by Level 2H earthquake motion is shown in Figure 9.2 (Solid line). The standards for verification of the cross-sectional strength against out-of-plane shear forces are achieved.

(2) Verification of relative displacement between tank Wall and bottom slab
The results of verification of the relative displacement between the wall and the bottom slab are shown in Figure 9.10. The limit values are the allowable displacement as determined by the fatigue limit of the membrane and the radial relative displacement established considering the structure of the slab fitted between the wall and the bottom slab (to absorb the relative displacement). The relative displacement between the tank wall and the bottom slab is less than the limit value for verification (4.5 cm). Thus, the joint between the wall and the bottom slab is considered to have the desired deformation capacity.

(3) Verification of deformation of upper extremity of the wall
The time history waveform of oval deformation of the wall rim is shown in Figure 9.11. This figure indicates the radial relative displacement at the rim of the wall at 0° and at 180°. The relative displacement of wall rim is below the limit value for verification as determined by the deformation capacity of the roof (8.7 cm). The wall is, therefore, considered to have the desired deformation capacity.

![Figure 9.6 Distribution of compressive principal strain (maximum value)](image)

![Figure 9.7 Time history of compressive principal strain](image)
Figure 9.8 Distribution of tensile principal strain (maximum value)

Figure 9.9 Time history of tensile principal strain

Figure 9.10 Time history of relative displacement between wall and bottom slab

Figure 9.11 Time history of deformation of wall rim
10. COMPARISON OF VERIFICATION BY METHODS 2 AND 3

10.1 RELATIONSHIP BETWEEN SECTIONAL FORCE AND STRAIN

Method 3 represents the nonlinearity of the main wall structure of the wall using a member-level history-dependent macro model. Figure 10.1 shows the relationship between in-plane shear force and in-plane shear strain for elements in this model for which the in-plane shear force is predominant (97.5° AP-2.7m). On the other hand, Method 2 treats the nonlinearity of a member as an equivalent stiffness and sets it at a level one-third of the initial stiffness (Figure 10.1). Method 3 yields lower stiffness in comparison with the increase in in-plane shear force than Method 2 does. As a result, Method 3 is capable of analyzing the deformation of members more accurately after the reinforcement has yielded.

![Figure 10.1 Relationship between in-plane shear force and shear strain (97.5° AP-2.7m)](image)

10.2 COMPARISON OF AMOUNT OF REINFORCEMENT REQUIRED

The amount of main reinforcement is determined on the basis of the sectional forces determined by analysis using Level 1 earthquake motion. The deformation capacity of the in-ground LNG tank is then checked against Level 2H earthquake motion by analysis using Method 3 (the dynamic nonlinear analysis method). This procedure demonstrates that the in-ground LNG tank has the desired deformation capacity. Using Method 2 (the quasi-dynamic equivalent linear analysis method), on the other hand, the reinforcement is arranged so as to provide adequate strength to withstand the sectional forces obtained in analysis for Level 2H earthquake motion.

The amounts of main reinforcement determined using Methods 2 and 3 are compared in Figure 8.2. The reinforcement arrangement determined using Method 3 contains about 400 t less steel than when using Method 2. The amount of shear reinforcement is the same with both methods (Figure 9.2).

11. EFFECT OF STREAMLINING BY MOW SOPHISTICATED ANALYSIS METHOD

By checking the deformation capacity of the main structure of an in-ground LNG tank using a dynamic
nonlinear analysis method (Method 3), it is found that less reinforcement is required than when a quasi-dynamic equivalent linear analysis method (Method 2) is used.

When implementing Method 2, the equivalent stiffness is set such that the cross-sectional strength is sufficiently high for a safe-side design. As a result, this method determines the amount of reinforcement required to withstand Level 2 earthquake motion and thereby secure the required cross-sectional strength. With Method 3, on the other hand, deformation beyond yielding of the reinforcement can be analyzed, so it is possible to design the structure to withstand larger Level 2 earthquake motion by making effective use of the deformation capacity of members and thus absorbing the energy. As a result, since Method 3 determines the amount of reinforcement on the basis of Level 1 earthquake motion as shown in Table 11.1, less reinforcement is required than when using Method 2.

<table>
<thead>
<tr>
<th>Method</th>
<th>Seismic Performance 1</th>
<th>Seismic Performance 2</th>
<th>Seismic performance 3</th>
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<tbody>
<tr>
<td>Method 2</td>
<td>Verification of yield strength</td>
<td>Verification of ultimate strength</td>
<td>Verification of ultimate strength</td>
</tr>
<tr>
<td>Method 3</td>
<td>Verification of yield Strength (Method 2 substituted)</td>
<td>Verification of deformation capacity</td>
<td>Verification of deformation capacity</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Verification of out-of-plane shear strength</td>
<td>Verification of out-of-plane shear strength</td>
</tr>
</tbody>
</table>

Legend

Combination of analysis methods used for determination of amount of reinforcement and seismic performance

From the above discussion, it is clear that the use of the more sophisticated analysis method results in a more accurate analysis of member and element behavior. This in turn means that the safety allowance can be reduced and allows for more streamlined design of the main structure of an in-ground LNG tank.

Acknowledgements

This case study was carried out as one of the activities of the Subcommittee for Streamlining the Design of In-ground LNG Tanks, Committee of Civil Engineering for Energy Equipment, Japan Society of Civil Engineers. Valuable advice with regard to preparing the case study was offered by President Hajime Okamura of Kochi University of Technology, the chairman of the subcommittee, and various subcommittee members. The authors would like to express their sincere thanks to these people.

References
